



Research In Progress

Project Title: Advanced Crash Avoidance Technologies Program (ACAT) II – Nissan/University of Michigan Transportation Research Institute (UMTRI)

Project Manager: John Harding

Description: The Nissan/UMTRI ACAT project is focused on driver situational awareness in relation to lane-change/merge maneuvers that can result in crashes.

Project Initiation Date: January 1, 2009

Close Date: December 31, 2010

Contract Number: DTNH22-08-H-00237

Project Awarded To: Nissan-UMTRI

Total Contract Cost: The cooperative agreement total is \$2,343,800.00 with the government share of \$1,000,000.00. Current funding obligated is \$332,922.50.

Date Added: