Research In Progress

**Project Title:** Advanced Crash Avoidance Technologies Program (ACAT) II – Nissan/University of Michigan Transportation Research Institute (UMTRI)

**Project Manager:** John Harding

**Description:** The Nissan/UMTRI ACAT project is focused on driver situational awareness in relation to lane-change/merge maneuvers that can result in crashes.

**Project Initiation Date:** January 1, 2009

**Close Date:** December 31, 2010

**Contract Number:** DTNH22-08-H-00237

**Project Awarded To:** Nissan-UMTRI

**Total Contract Cost:** The cooperative agreement total is $2,343,800.00 with the government share of $1,000,000.00. Current funding obligated is $332,922.50.